

What my deep model doesn't know...

Principled and practical uncertainty estimates in deep learning without changing a thing.

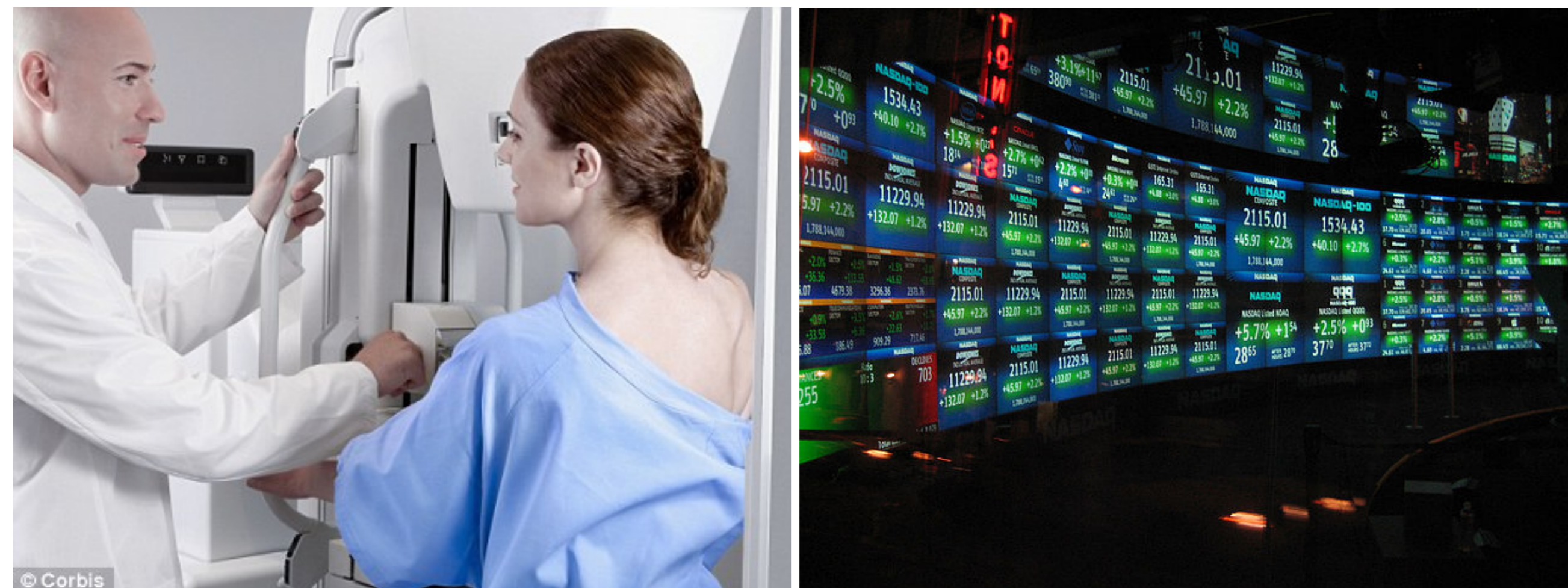
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Uncertainty is Everywhere.



Train a model to recognise dog breeds; someone will try to classify a cat.



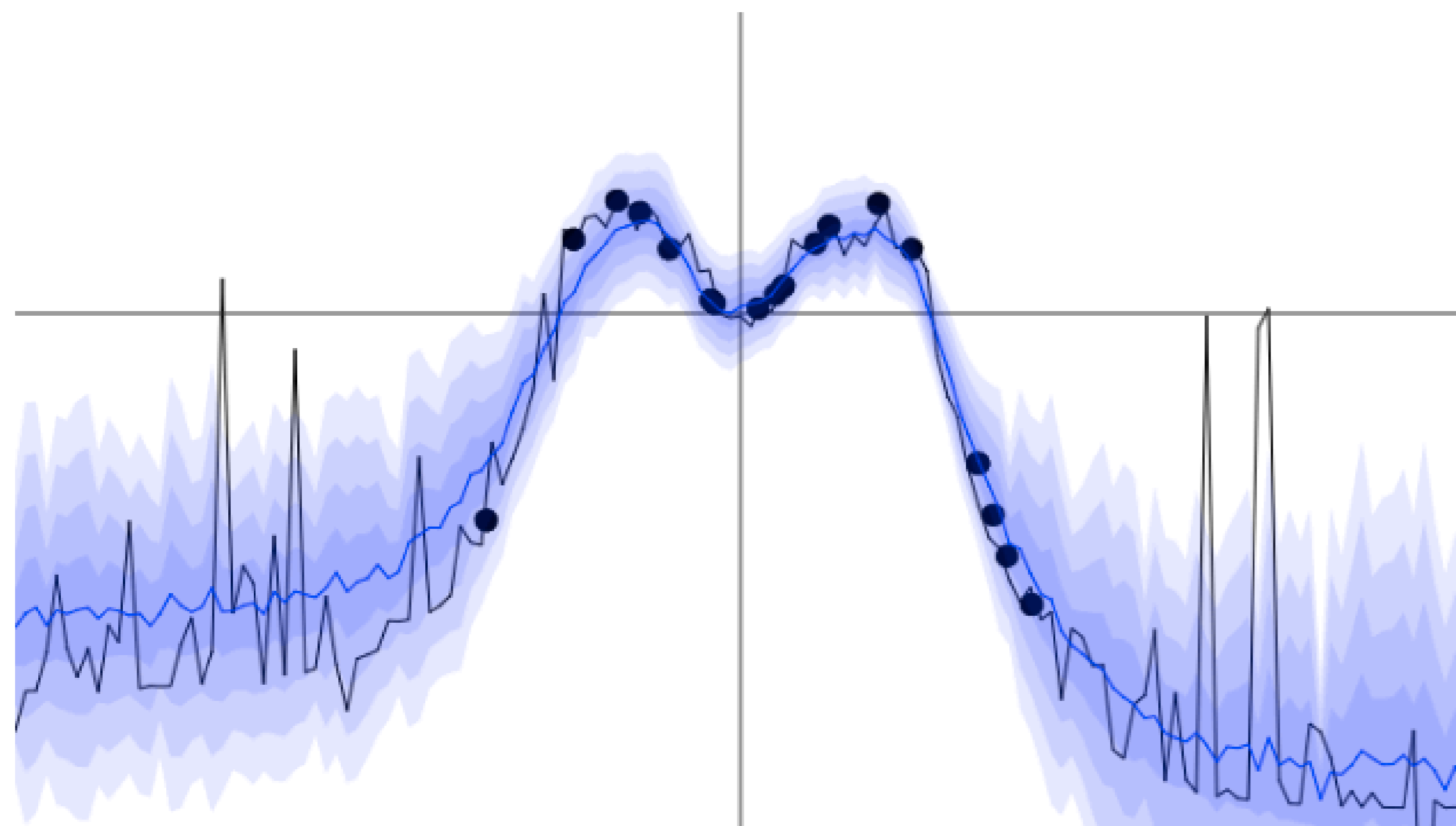
But also in decision making, life sciences, medicine, bioinformatics, self-driving cars, algo-trading...

For the practitioner:

- model diagnosis – *model should be certain about what it should know*
- use specialised models – *with simple and fast models for most data*
- critical systems – *pass data to a human to decide*

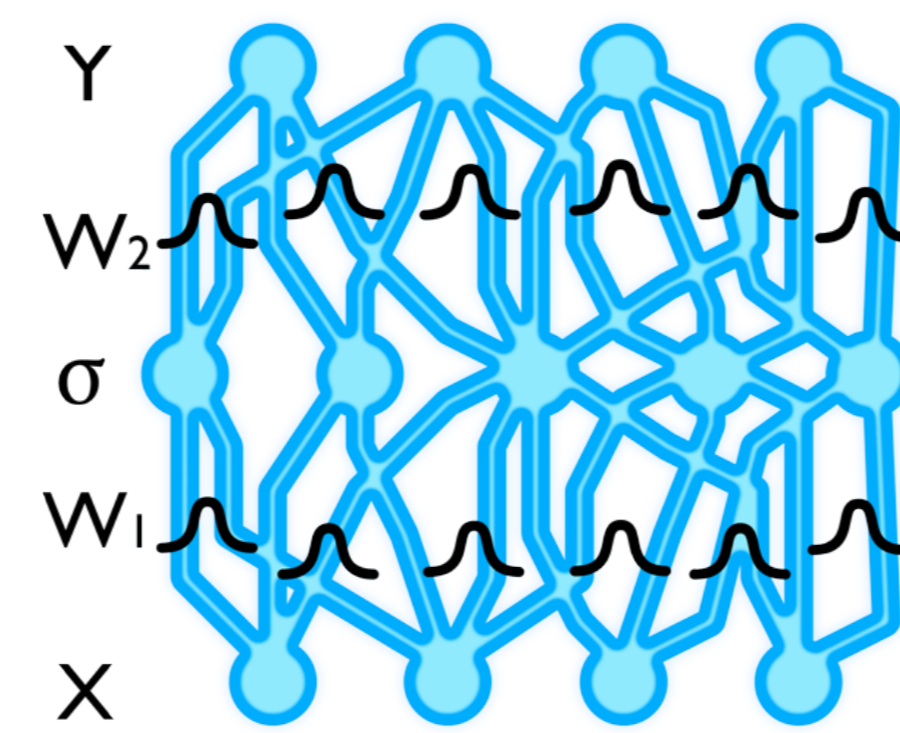
Uncertainty in Bayesian modelling

- Observed inputs $\mathbf{X} = \{\mathbf{x}_i\}_{i=1}^N$ and outputs $\mathbf{Y} = \{\mathbf{y}_i\}_{i=1}^N$
- Capture distribution believed to have generated outputs
- Look at the first two moments:



From Bayesian modelling to Dropout

- Place prior dist. $p(\mathbf{W})$ on weights, making these r.v.s



- Given dataset \mathbf{X}, \mathbf{Y} , the r.v. \mathbf{W} has a posterior: $p(\mathbf{W}|\mathbf{X}, \mathbf{Y})$
- Which is difficult to evaluate...
- We can define a simple distribution $q_\theta(\cdot)$ and approximate

$$q_\theta(\mathbf{W}) \approx p(\mathbf{W}|\mathbf{X}, \mathbf{Y})$$

- Inference with

$$q_\theta(\mathbf{W}) := \mathbf{M} \cdot \text{diag}(\text{Bernoulli})$$

and parameter \mathbf{M}

= Dropout training.

Practical Uncertainty Estimates

Using dropout we fit a distribution...

- Use first moment for predictions:

$$\mathbb{E}(\mathbf{y}^*) \approx \frac{1}{T} \sum_{t=1}^T \hat{\mathbf{y}}_t$$

- Use second moment for uncertainty (in regression):

$$\text{Var}(\mathbf{y}^*) \approx \frac{1}{T} \sum_{t=1}^T \hat{\mathbf{y}}_t^T \hat{\mathbf{y}}_t - \mathbb{E}(\mathbf{y}^*)^T \mathbb{E}(\mathbf{y}^*) + \tau^{-1} \mathbf{I}$$

with $\hat{\mathbf{y}}_t \sim \text{DropoutNetwork}(\mathbf{x}^*)$.

In more practical terms, given point x :

- drop units at test time
- repeat 10 times
- and look at mean and sample variance.

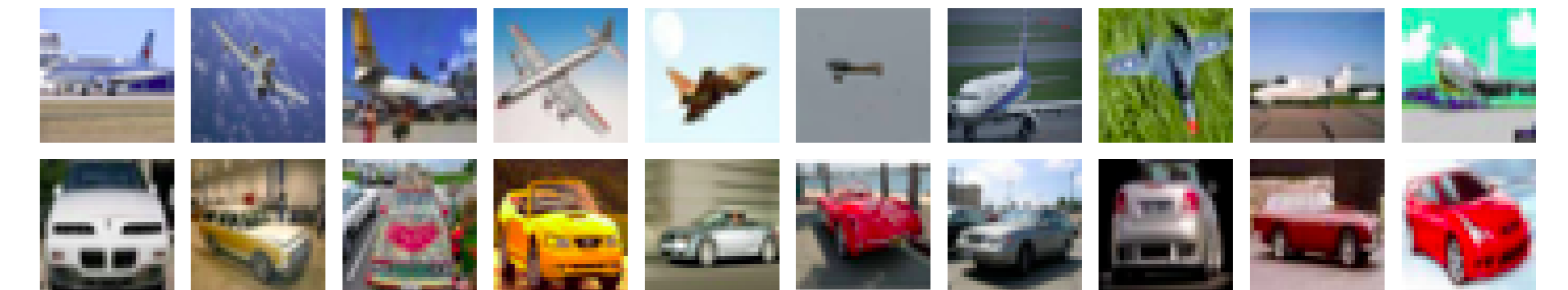
Or in Python:

```
y = []
for _ in xrange(10):
    y.append(model.output(x, dropout=True))
y_mean = numpy.mean(y)
y_var = numpy.var(y)
```

Using the predictive mean

Model	CIFAR-10 Test Error (and Std.)	
	Standard Dropout	Bayesian technique
NIN	10.43 (Lin et al., 2013)	10.27 ± 0.05
DSN	9.37 (Lee et al., 2014)	9.32 ± 0.02
Augmented-DSN	7.95 (Lee et al., 2014)	7.71 ± 0.09

Bayesian techniques with existing CIFAR-10 state-of-the-art

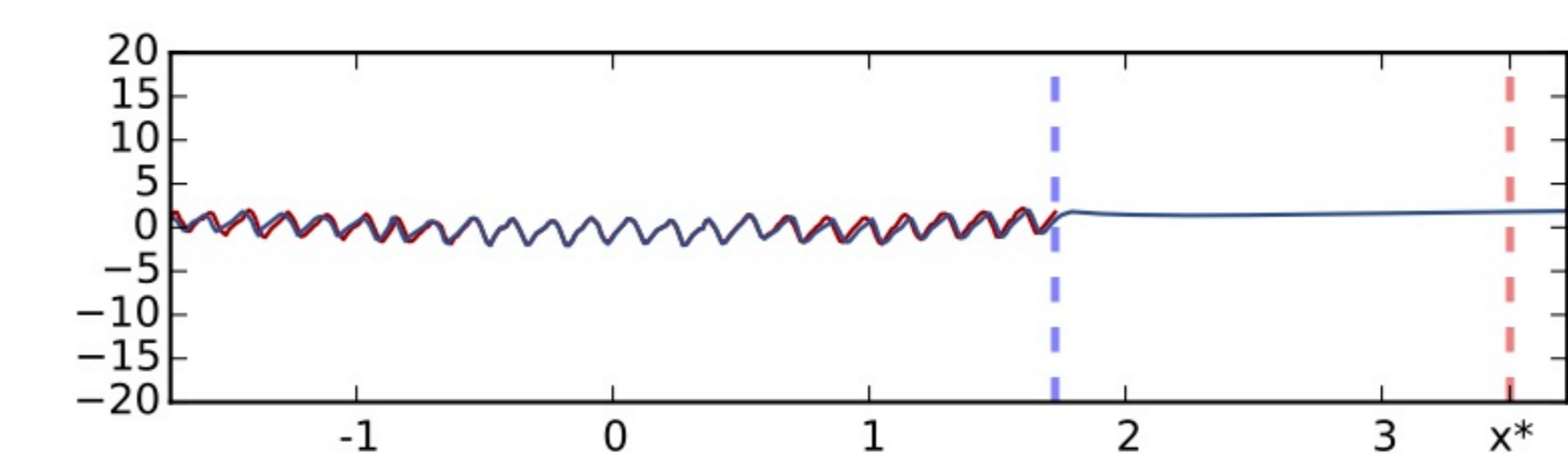


More results at yarin.co/BCNN

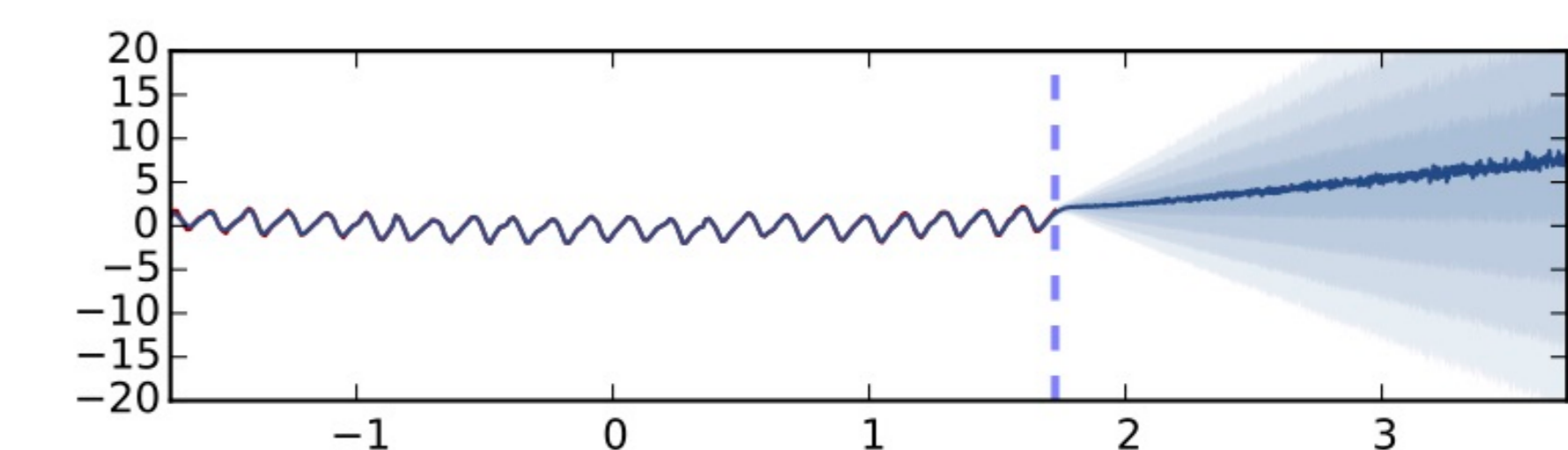
Using the predictive variance

What would be the CO₂ level in Mauna Loa, Hawaii, in 20 years' time?

- Normal dropout (weight averaging, 5 layers, ReLU units):



- Same network, Bayesian perspective:



Online demos at yarin.co/blog

And in numbers...

Dataset	Avg. Test RMSE and Std. Errors			Avg. Test LL and Std. Errors		
	VI	PBP	Dropout	VI	PBP	Dropout
Boston Housing	4.32 ± 0.29	3.01 ± 0.18	2.97 ± 0.85	-2.90 ± 0.07	-2.57 ± 0.09	-2.46 ± 0.25
Concrete Strength	7.19 ± 0.12	5.67 ± 0.09	5.23 ± 0.53	-3.39 ± 0.02	-3.16 ± 0.02	-3.04 ± 0.09
Energy Efficiency	2.65 ± 0.08	1.80 ± 0.05	1.66 ± 0.19	-2.39 ± 0.03	-2.04 ± 0.02	-1.99 ± 0.09
Kin8nm	0.10 ± 0.00	0.10 ± 0.00	0.10 ± 0.00	0.90 ± 0.01	0.90 ± 0.01	0.95 ± 0.03
Naval Propulsion	0.01 ± 0.00	0.01 ± 0.00	0.01 ± 0.00	3.73 ± 0.12	3.73 ± 0.01	3.80 ± 0.05
Power Plant	4.33 ± 0.04	4.12 ± 0.03	4.02 ± 0.18	-2.89 ± 0.01	-2.84 ± 0.01	-2.80 ± 0.05
Protein Structure	4.84 ± 0.03	4.73 ± 0.01	4.36 ± 0.04	-2.99 ± 0.01	-2.97 ± 0.00	-2.89 ± 0.01
Wine Quality Red	0.65 ± 0.01	0.64 ± 0.01	0.62 ± 0.04	-0.98 ± 0.01	-0.97 ± 0.01	-0.93 ± 0.06
Yacht Hydrodynamics	6.89 ± 0.67	1.02 ± 0.05	1.11 ± 0.38	-3.43 ± 0.16	-1.63 ± 0.02	-1.55 ± 0.12
Year Prediction MSD	9.034 ± NA	8.879 ± NA	8.849 ± NA	-3.622 ± NA	-3.603 ± NA	-3.588 ± NA

Table 1: Average test performance in RMSE and predictive log likelihood for a popular variational inference method (VI, Graves [20]), Probabilistic back-propagation (PBP, Hernández-Lobato and Adams [27]), and dropout uncertainty (Dropout).

More results at yarin.co/dropout

Full paper: "Dropout as a Bayesian Approximation: Representing Model Uncertainty in Deep Learning". Photos taken from Wikimedia or original work.